



**Barcelona
Supercomputing
Center**
Centro Nacional de Supercomputación



EXCELENCIA
SEVERO
OCHOA

Parallel Programming

Prof. Jesús Labarta
BSC & UPC

Barcelona, July 1st 2019

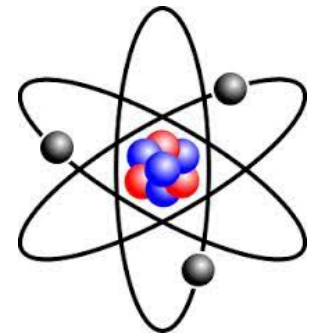
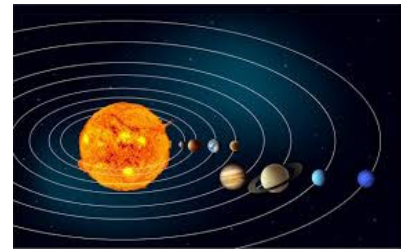
What am I doing here ?



Already used in Mateo12

“As below, so above”

- Leverage computer architecture background ...
- ... in higher levels of the system stack
- Looking for further insight



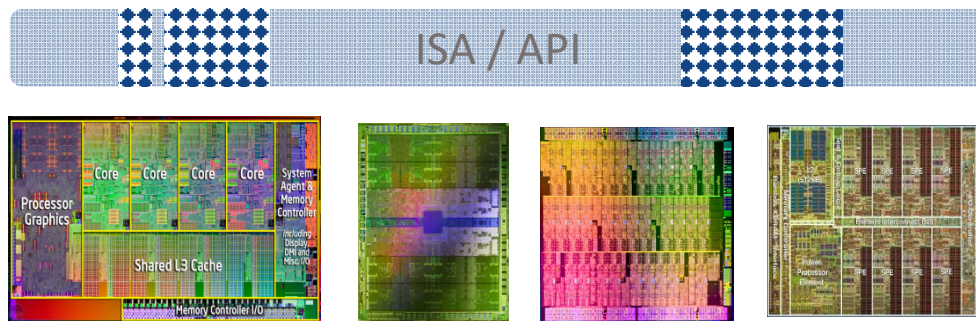
The Programming model osmotic membrane

Applications

PM: High-level, clean, abstract interface

Power to the runtime

What is the right degree of porosity ?



Integrate concurrency and data

Single mechanism

Concurrency:

- Dependences built from data accesses

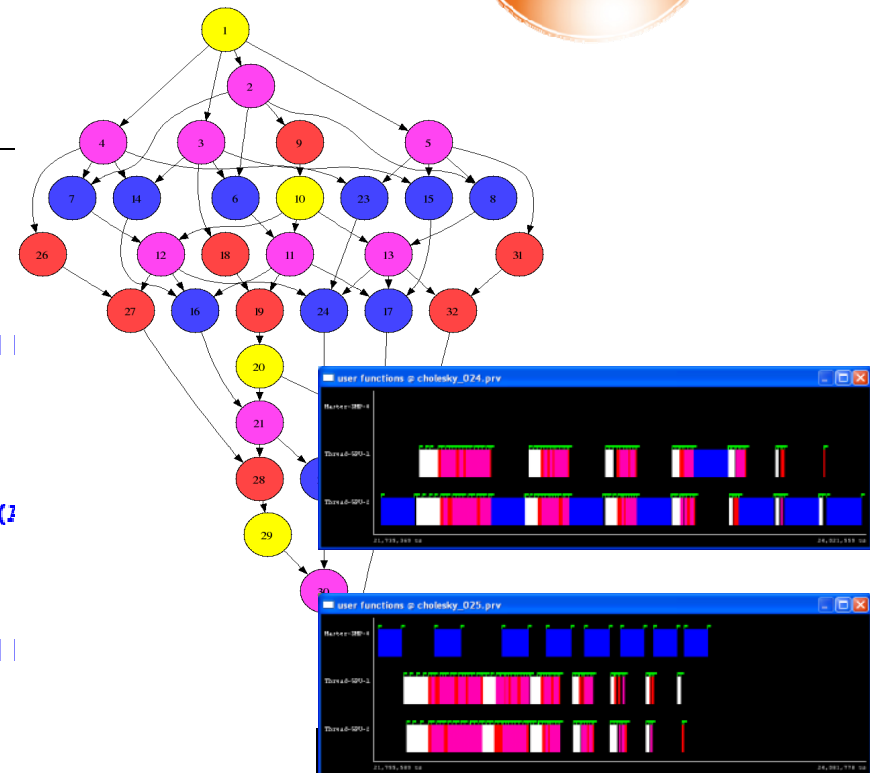
- Lookahead: About instantiating work

Locality & data management

- From data accesses

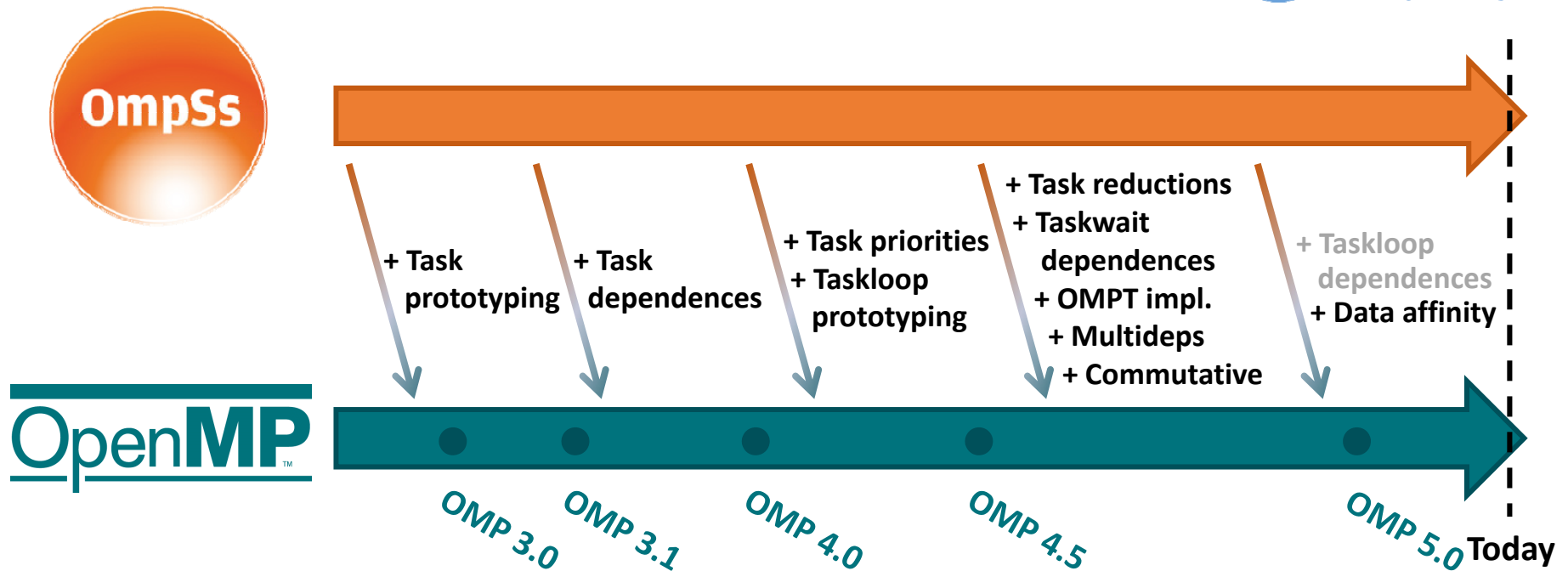


```
void Cholesky(int NT, float *A[NT][NT] ) {  
  for (int k=0; k<NT; k++) {  
    #pragma omp task inout ([TS][TS](A[k][k]))  
    ● spotrf (A[k][k], TS) ;  
    for (int i=k+1; i<NT; i++) {  
      #pragma omp task in([TS][TS](A[k][k])) inout ([TS][TS](A[k][i]))  
      ● strsm (A[k][k], A[k][i], TS);  
    }  
    for (int i=k+1; i<NT; i++) {  
      for (j=k+1; j<i; j++) {  
        #pragma omp task in([TS][TS](A[k][i]), [TS][TS](A[k][j])) inout ([TS][TS](A[j][i]))  
        ● sgemm ( A[k][i], A[k][j], A[j][i], TS);  
      }  
      #pragma omp task in ([TS][TS](A[k][i])) inout([TS][TS](A[i][i]))  
      ● ssyrk (A[k][i], A[i][i], TS);  
    }  
  }  
}
```



OmpSs

- A forerunner for OpenMP



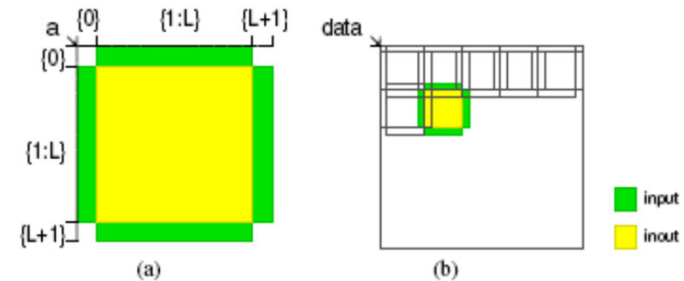
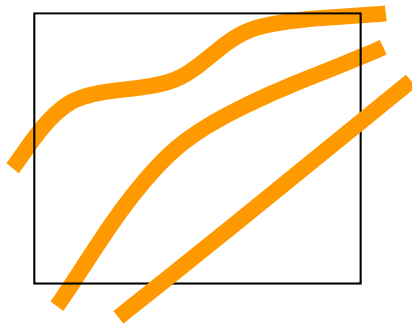
Important topics/practices

- Regions
- Nesting
- Taskloops + dependences
- Hints
- Taskify communications: MPI Interoperability
- Malleability
- Homogenize Heterogeneity
- Hierarchical “acceleration”
- Memory management & Locality

Are these topics relevant at ISA level?
Can some of these things be leveraged?
Are they already there?

Regions

- Precise nD subarray accesses
 - “Complex” analysis but ...
- Enabler for ...
 - Recursion
 - Flexible nesting
 - Taskloop dependences
 - Data management
 - locality
 - layout



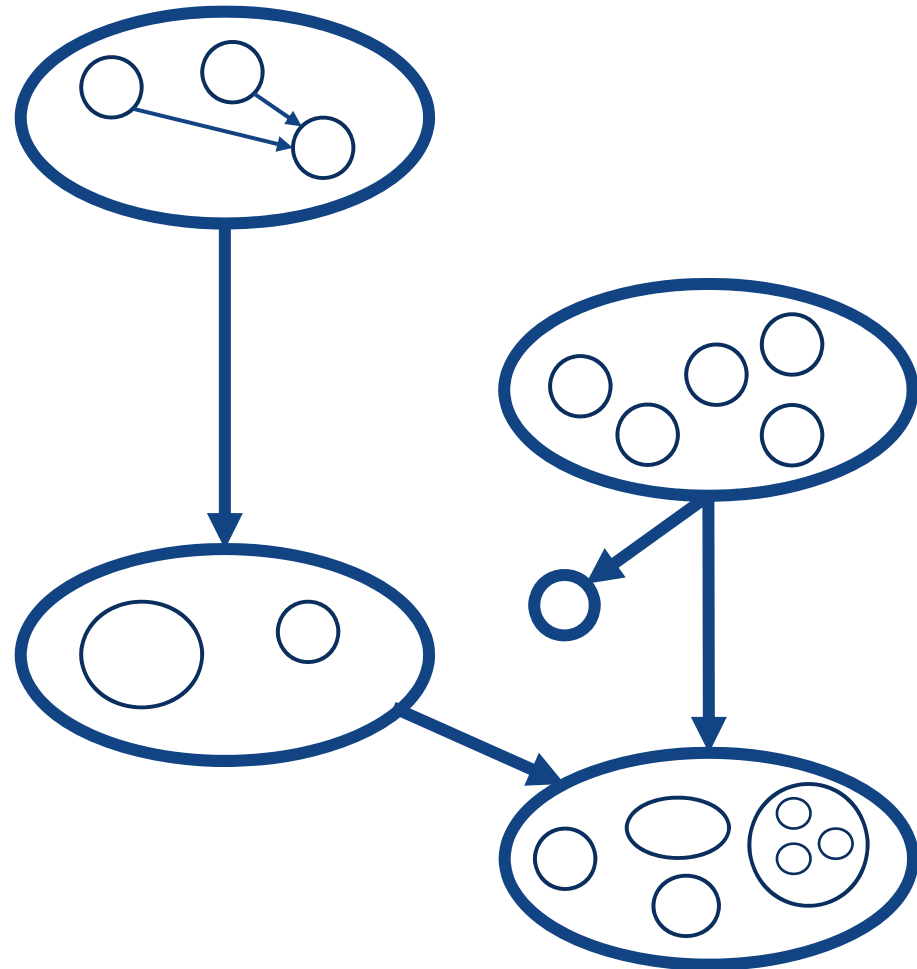
```
void gs (float A[(NB+2)*BS][(NB+2)*BS])
{
    int it,i,j;

    for (it=0; it<NITERS; it++)
        for (i=0; i<N-2; i+=BS)
            for (j=0; j<N-2; j+=BS)
                gs_tile(&A[i][j]);
}
```

```
#pragma omp task \
    in(A[0][1;BS], A[BS+1][1;BS], \
        A[1;BS][0], A[1;BS][BS+1]) \
    inout(A[1;BS][1;BS])
void gs_tile (float A[N][N])
{
    for (int i=1; i <= BS; i++)
        for (int j=1; j <= BS; j++)
            A[i][j] = 0.2*(A[i][j] + A[i-1][j] +
                A[i+1][j] + A[i][j-1] +
                A[i][j+1]);
}
```

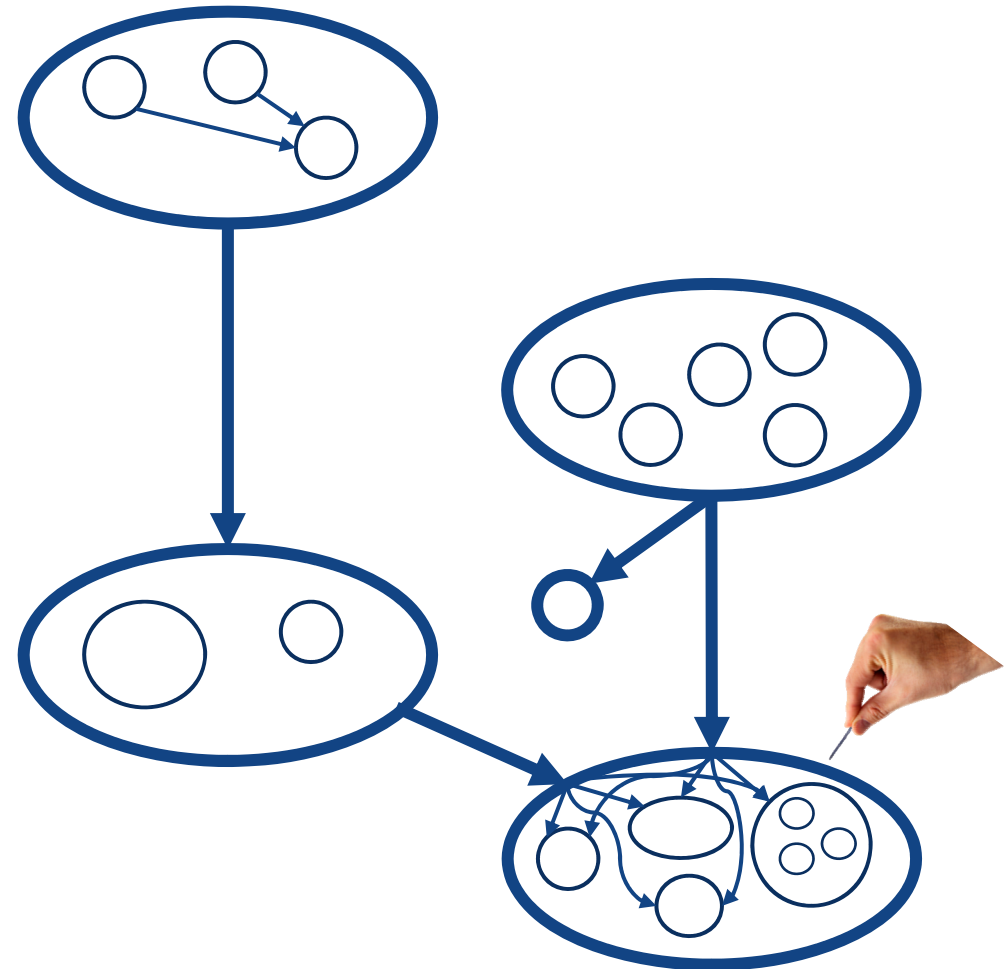
Nesting

- Top down
 - Every level contributes
- Flattening dependence graph
 - Increase concurrency
 - Take out runtime overhead from critical path
- Granularity control
 - final clauses, runtime



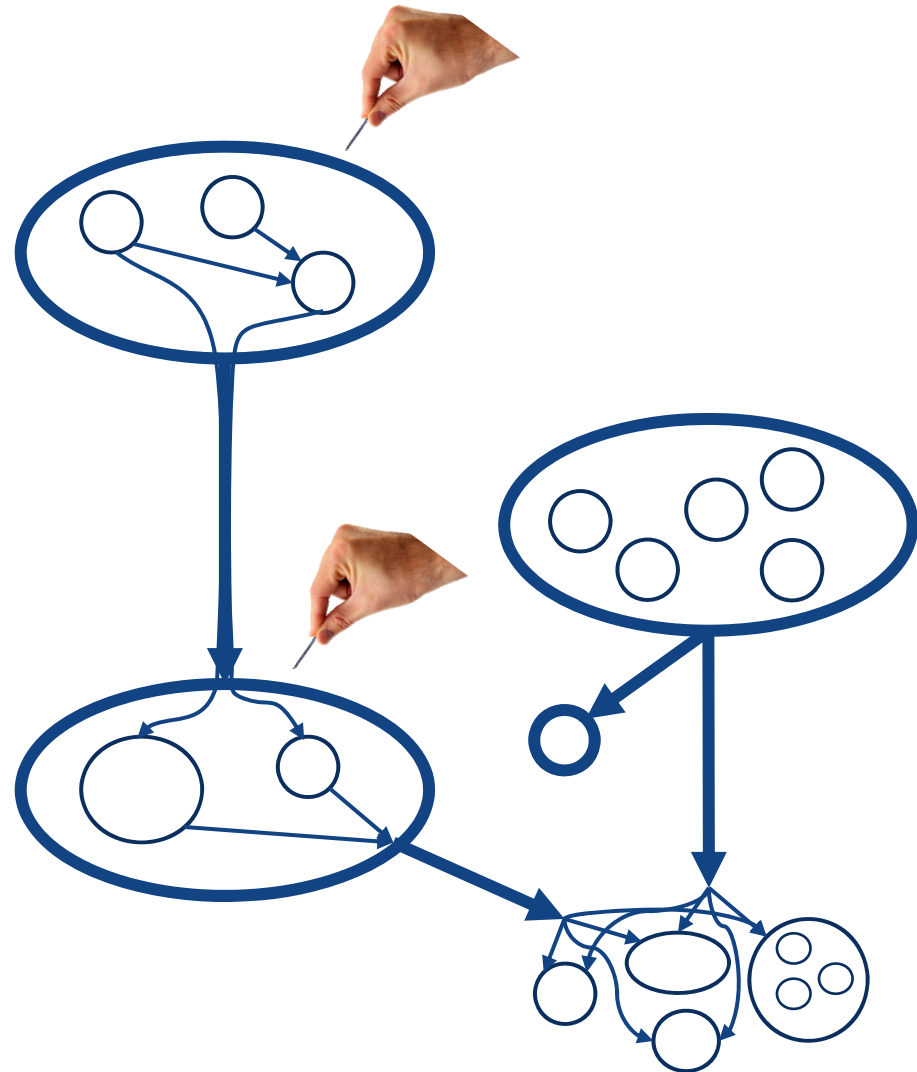
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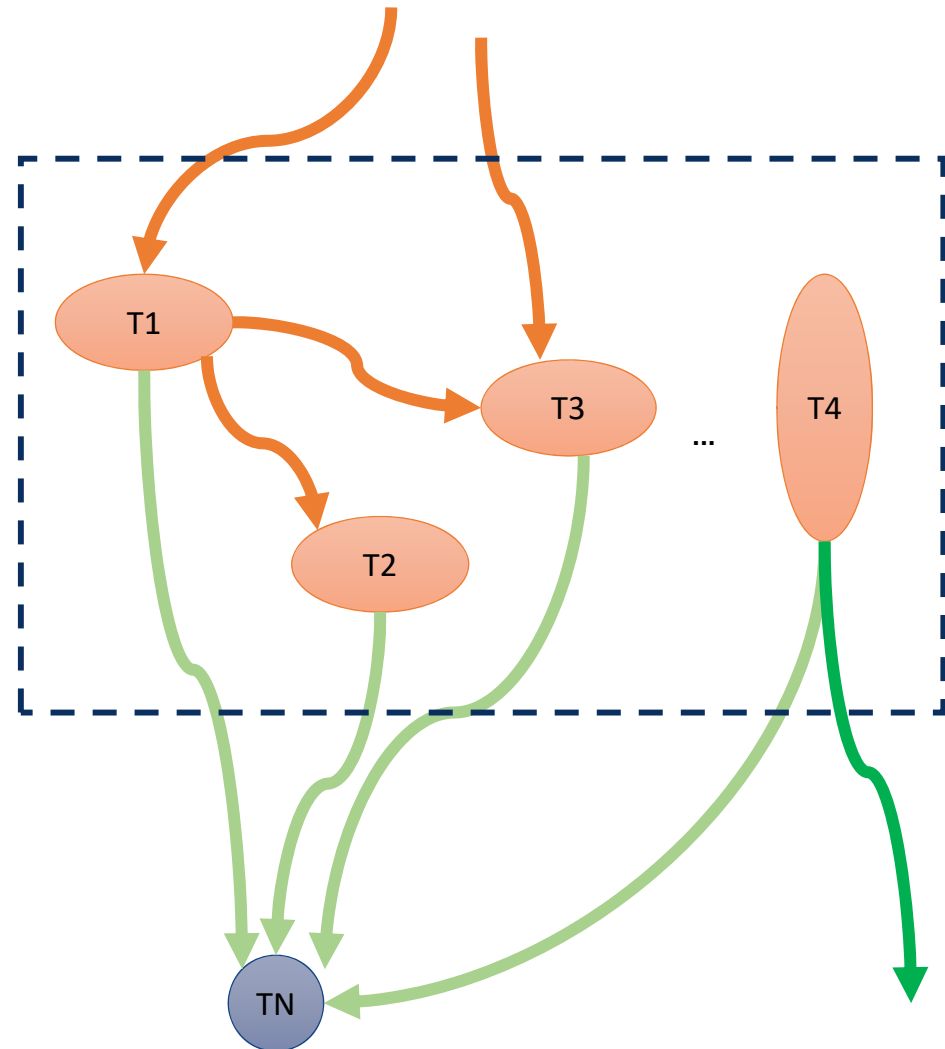
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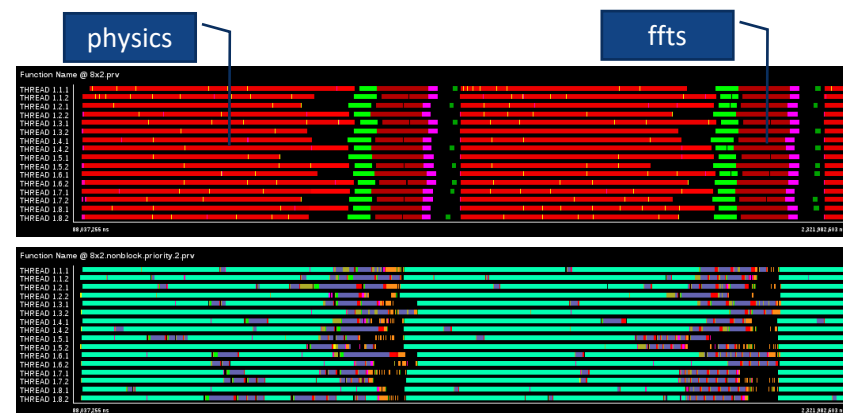
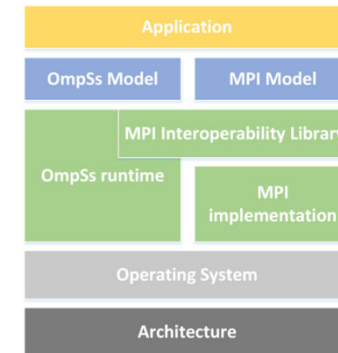
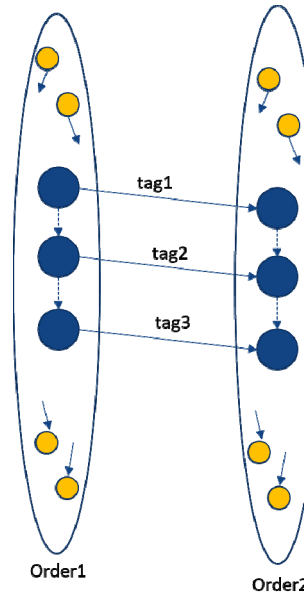
Taskloops & dependences

- Dependences
 - Intra loop
 - Inter loops
- Dynamic granularities
 - Guided
 - Runtime
- Combination
 - Enabled by regions support



Taskifying MPI calls

- MPI: a “fairly sequential” model
- Taskifying MPI calls
 - Opportunities
 - Overlap/out of order execution
 - Provide laxity for communications
 - Migrate/aggregate load balance issues
 - Risk to introduce deadlocks
- TAMPI
 - Virtualize “communication resource”



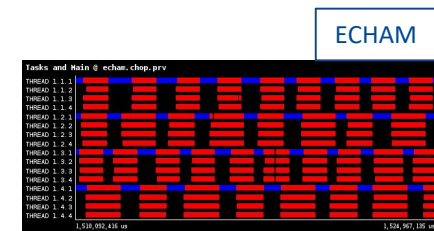
IFS weather code kernel. ECMWF

V. Marjanovic et al, “Overlapping Communication and Computation by using a Hybrid MPI/SMPs Approach” ICS 2010

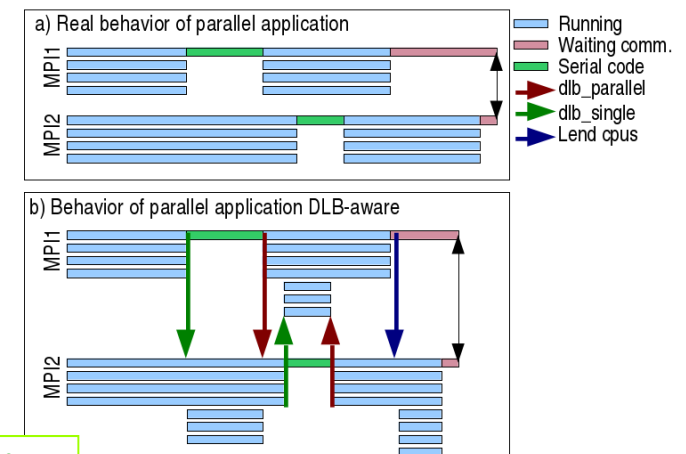
K. Sala et al, "Extending TAMPI to support asynch MPI primitives". OpenMPCon18

Exploiting malleability

- Malleability
 - ~~Omp_get_thread_num, Thread private, large parallels~~
- Dynamic Load Balance & Resource management
 - Intra/inter process/application
- Library (DLB)
 - Runtime interception (MPIP, OMPT, ...)
 - API to hint resource demands
 - Core reallocation policy
- Opportunity to fight Amdahl's law
 - Productive / Easy !!!
 - Hybridize only imbalanced regions
 - Nx1



<https://pm.bsc.es/dlb>



Homogenizing Heterogeneity

- Performance heterogeneity
- ISA heterogeneity
- Several non coherent address spaces

Criticality-awareness in heterogeneous architectures

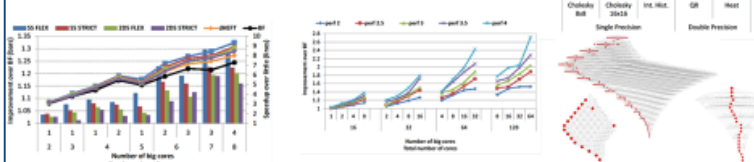
- Heterogeneous multicores
 - ARM big.LITTLE 4 A-15@2GHz; 4A-7@1.4GHz
 - Tasksim simulator: 16-256 cores; 2-4x



Kernel	#Tasks	Measured Perf. Ratio
Cholesky B8	120	
Cholesky 512x16	816	2.23
Integer Histogram	2048	1.71
QR	1488	0.26
Heat diffusion	5124	2.83

- Runtime approximation of critical path
 - Implementable, small overhead that pay off
 - Approximation is enough

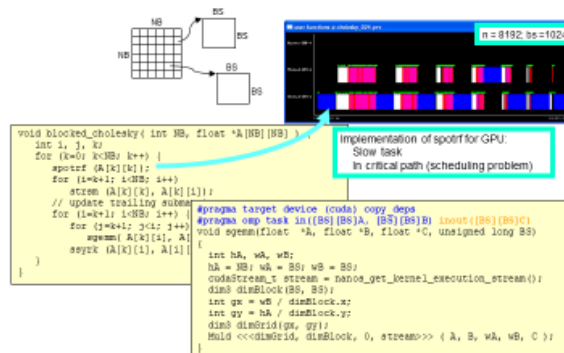
- Higher benefits the more cores, the more big cores, the higher performance ratio



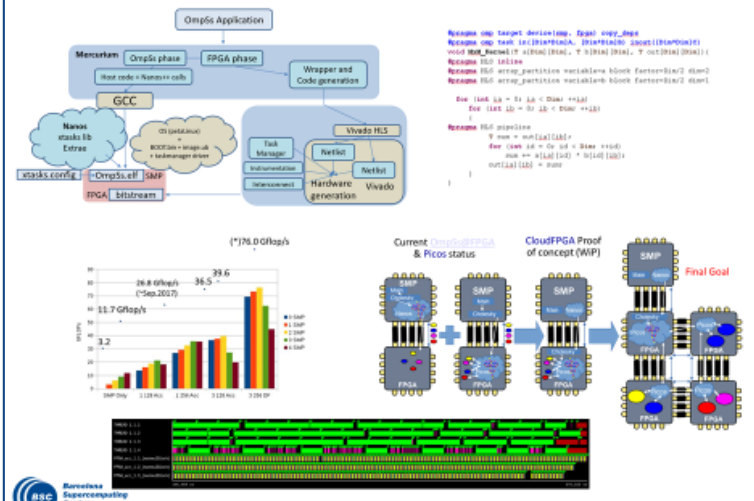
K. Chronaki et al., "Criticality-Aware Dynamic Task Scheduling for Heterogeneous Architectures," ICS 2015

Homogenizing Heterogeneity

- Flexibility
 - Towards a source code independent of number or type devices
 - Small modification in source to achieve huge changes in execution order
 - "Controllable"

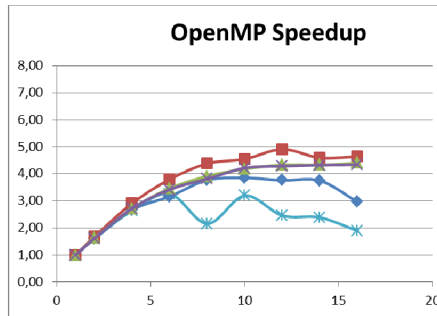


OmpSs @ FPGA

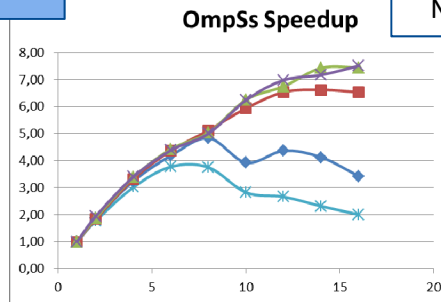


On the OmpSs road

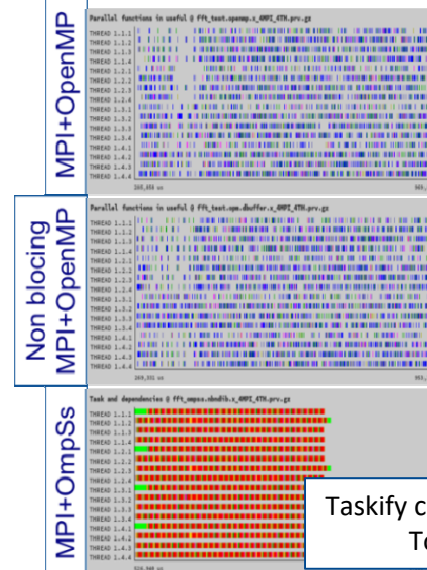
Lulesh



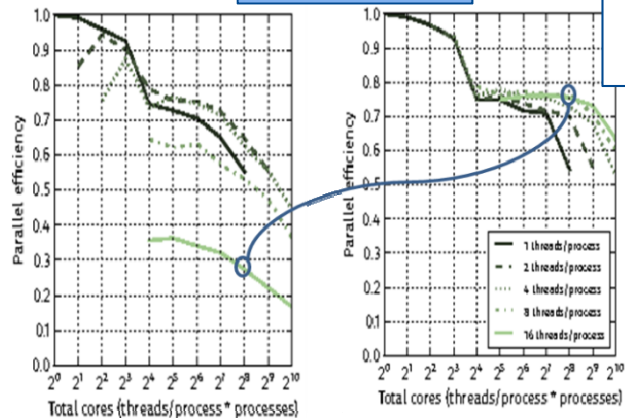
Top down
Nesting



FFTLib (QE miniapp)



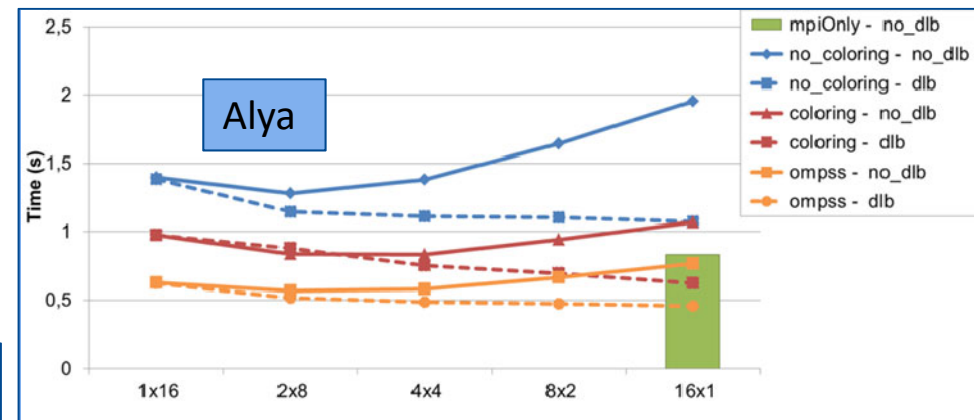
NT-CHEM



Taskify
communications
Top down

Dynamic Load Balance (DLB)
Commutative - multideps

Taskify communications
Top down



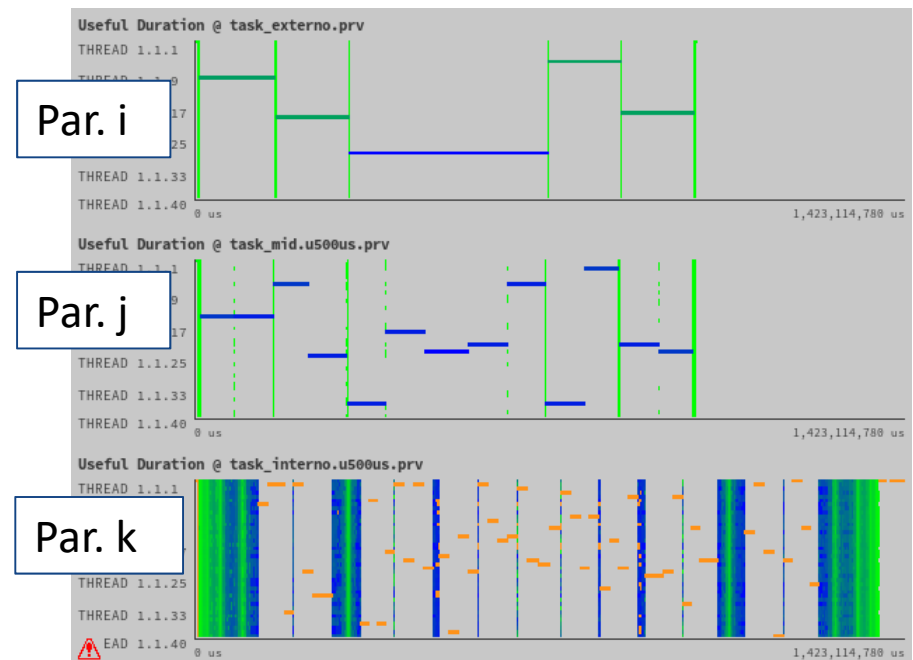
DMRG structure

- Density Matrix Renormalization Group app in condensed matter physics (ORNL)
- Skeleton
 - 3 nested loop
 - Reduction on large array
 - Huge variability of op cost
- Real miniapp
 - Different sizes of Y entries

```
T Y[N];  
  
for (i)  
  for (j)  
    for (k)  
      Y[i] += M[k] op X[j]
```

OpenMP parallelizations

- OpenMP parallelizations
 - Reduction
 - Based on full array privatization
 - Using reduction clauses
 - Nested parallels
 - Worksharings / Tasks
 - Synchronization at end of parallels exposes cost of load imbalances at all levels
 - Overheads at fine levels
 - Issues activation of multiple levels
 - Core partition
 - Levels of Privatization



Taskification

- Serialize reductions
 - Multiple dependence chains

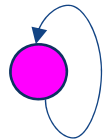
```
T Y[N];
```

```
for (i)
```

```
  for (j)
```

```
    for (k)
```

```
      Y[i] += M[k] op X[j]
```



Taskification

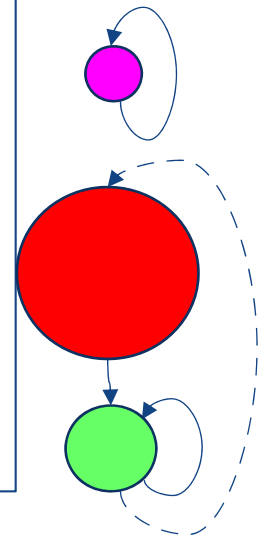
- Serialize reductions
 - Multiple dependence chains
- Split operations
 - Compute & reduce
 - Persist intermediate result
 - Global array of tmps
 - Used in a circular way
 - Enforce antidependence

```
T Y[N];
T tmp[Npriv];

for (i)
  for (j)
    for (k)
      if (small)
        Y[i] += M[k] op X[j]

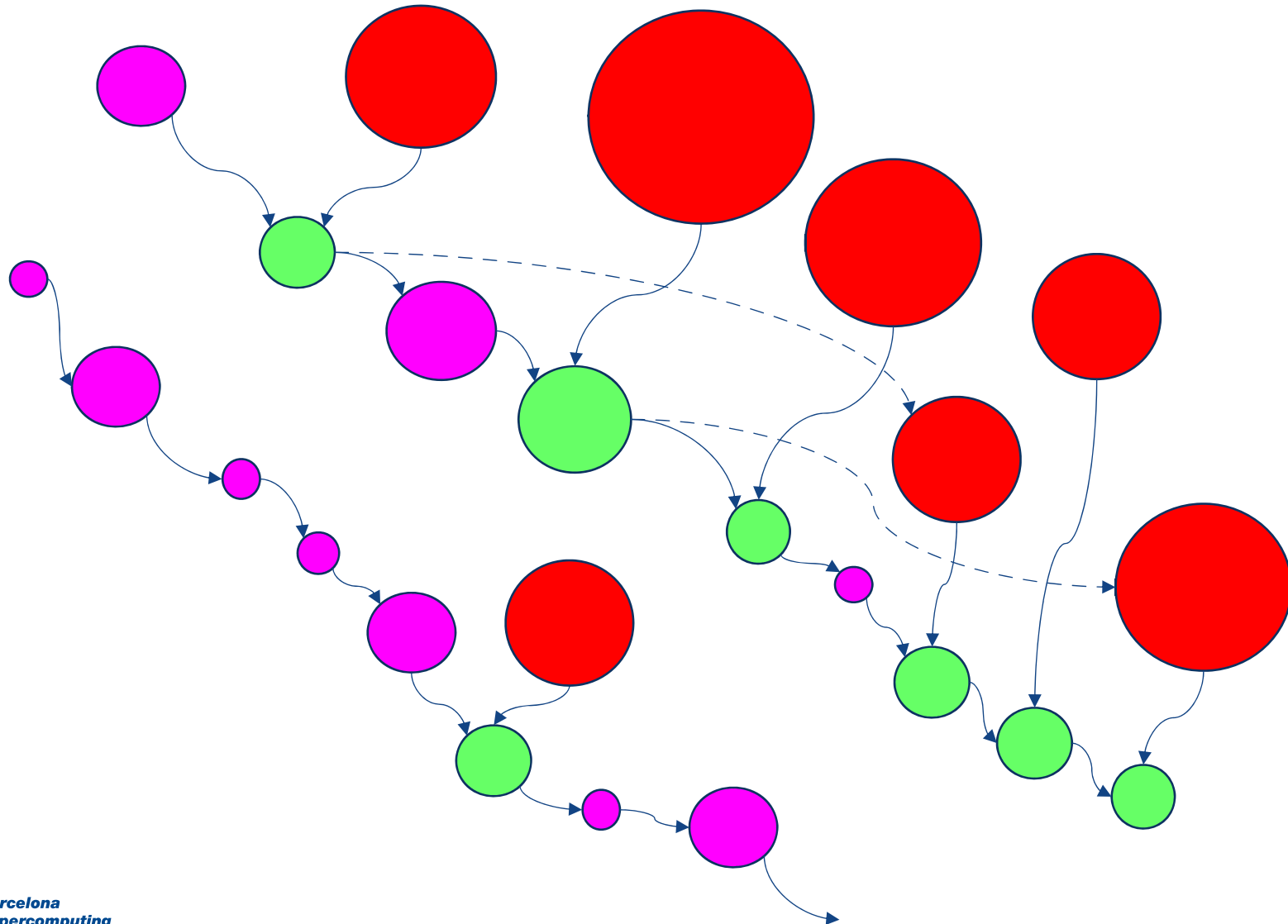
      else
        tmp[next]=M[k] op X[j]

    Y[i] += tmp[next];
```



- Reduce overhead → do not split small operation
 - Compute directly on target operand
 - Avoid task instantiation and dependence overhead
 - Avoid memory allocation, initialization & reduction to target operand

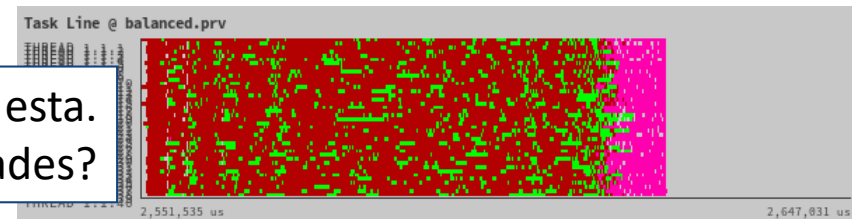
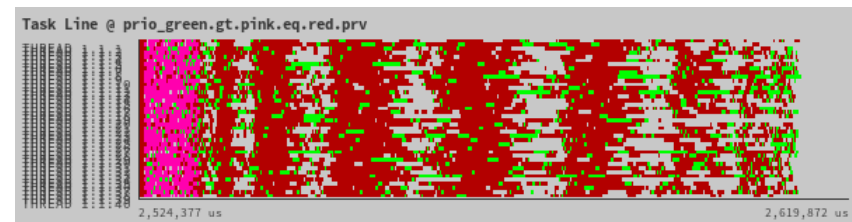
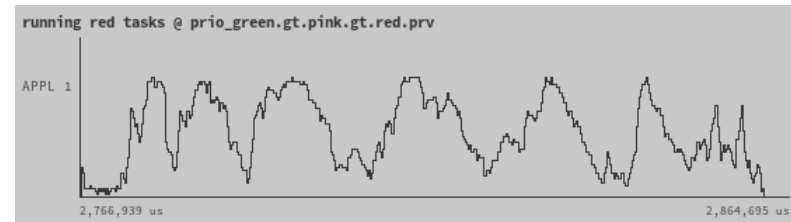
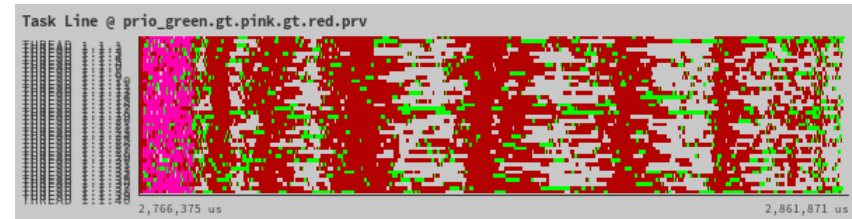
Resulting dependence chains



Performance ?

- Causes of pulsation of red tasks?
 - Instantiation order and granularity
 - Graph dependencies
- Improvements
 - Priorities
 - Anti-dependence distances
 - Nesting

Aqui tendria que poner la correspondiente sin prioridades



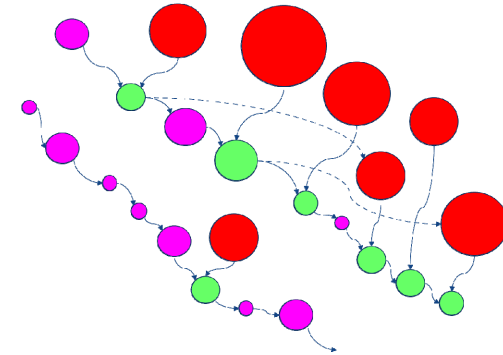
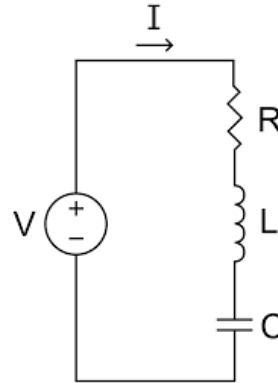
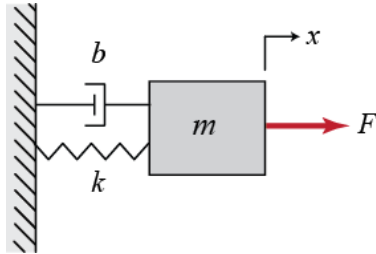
No tengo claro que era esta.
Que prioridades?

Aqui tendria que poner
correspondiente con ne:

Do these effects happen also at ISA level?

Can similar techniques be used to improve performance?

Question on graph scheduling dynamics



$$F = m\ddot{x} - b\dot{x} - kx$$

$$\omega_0 = \sqrt{k/m}$$

$$x(t) = Ae^{-\gamma t} \cos(\omega t - \varphi)$$

$$F(t) = F_0 \cos(\omega t) \rightarrow x(t) = A \cos(\omega t)$$

Effective k , m , b ?

Excitation ? Graph generation ?

Resources ?

Thanks to Yale

“There is no limit to what you can achieve provided
you do not care who takes the credit”

I first heard it from Yale

Thanks !



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Thanks